**Summary of Group Learning results**

**Predictive models applied in this study**

Four predictive models are applied in this experiment to investigate the effect of prediction performance on different permutations.

1. Linear SVM (SVM)
2. Group Learning (GL)
3. Neural network (NN)
4. Convolution neural network (CNN)

The detailed experimental settings are as follows:

- *positive class:* 16-digit matrix composed of digits ‘7’, ‘2’, ‘8’, ‘6’ (4 images for each digit, see Fig. 1);

- *negative class:* 16-digit matrix composed of digits ‘1’, ‘2’, ‘3’, ‘4’ (4 images for each digit, see Fig. 1);

- *feature vector (representing a 16-digit matrix)*

a. SVM: a real-valued vector of length 12544 (i.e., 16\*28\*28)

b. GL: 16 real-valued vectors of length 784 (i.e., 28\*28)

c. NN & CNN: a real-valued matrix of size 112x112

- number of training inputs/matrices: 20, 40, 80, 160, 320 (equally distributed in two classes)

- number of validation matrices: 20, 40, 80, 160, 320 (equally distributed in two classes)

- number of test matrices: 1000 (500 per class)

**Datasets**

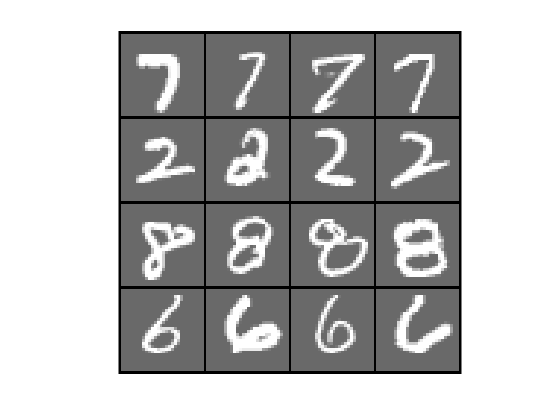
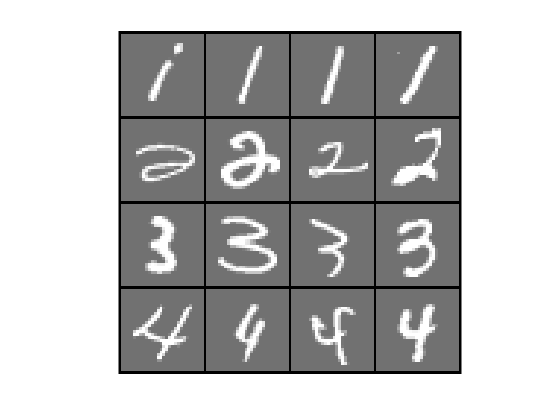
There are three types of 16-digit matrix datasets used in this experiment:

Dataset 1: Ordered matrix – see Fig. 1;

Dataset 2: Permuted-pixel matrix (**fixed** random pixel positions of whole matrix) – see Fig. 2;

Dataset 3: Permuted-image matrix (**varied** random image positions of whole matrix) – see Fig. 3.

Note that dataset 2 is generated by randomly permuting pixels of whole matrix in dataset 1, and the random pixel positions are fixed for all samples. Dataset 3 is generated by randomly permuting images of whole matrix in dataset 1, the positions of digit images are varied for each sample.

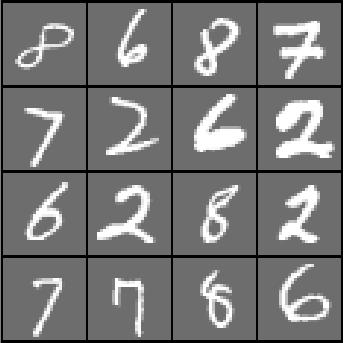
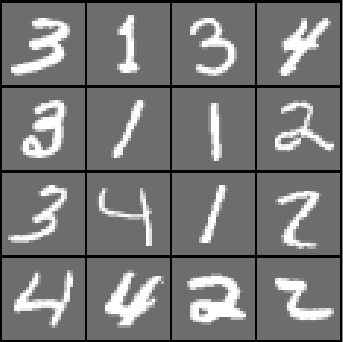
**Fig. 1.** Dataset 1, examples in positive (left) and negative (right) classes

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**Fig. 2.** Dataset 2, examples in positive (left) and negative (right) classes

**Fig. 3.** Dataset 3, examples in positive (left) and negative (right) classes

**Model selection**

The parameter C of SVM is selected via cross-validation, which generates the lowest validation error. GL is based on SVM, and the parameter C of SVM is selected via cross-validation as well. The real-valued outputs of SVM classifiers (corresponding to short group features) are combined to make a single prediction of GL. The threshold for making prediction of GL is estimated using validation data.

The parameters/structures of NN and CNN are used in the TensorFlow tutorials (<https://www.tensorflow.org/tutorials>) for classifying digit images in MNIST data. The NN has one hidden layer (regular densely-connected, 128 neurons, activation function = ‘ReLU’), and 20% neurons are randomly dropped-out. Two neurons in the output layer represent the predictions of two classes. The CNN is form (in sequence from first to last) by one convolution layer (with filters = 32, kernel size = 3x3, activation function = ‘ReLU’), one hidden layer (regular densely-connected, 128 neurons, activation function = ‘ReLU’), and one output layer (2 neurons).

**Result 1: Prediction performance of four models (SVM, GL, NN, CNN) on the three datasets**

The prediction (test) results of four models on datasets 1, 2, and 3 are shown in Tables 1, 2, and 3 correspondingly. Note that the training errors of all experiments (for all models applying to all datasets) are very small ~ 0.

For dataset 1, SVM and NN show the best prediction performance, both of them achieve SS=1.00, SP=1.00 for all training sample sizes (see Table 1). GL and CNN also show good prediction performance on dataset 1. However, when the training sample size is small, they make a small number of errors. This result may suggest that when the classification task is simple, and the training sample size is small, complex models (e.g., GL, CNN) may overfit the problem (because of the small training error ~ 0).

For dataset 2, the results are similar to the results of dataset 1 (see Tables 1 and 2). All models achieve good prediction performance. Especially for SVM, it still generates near-perfect classification. Randomizing the pixel positions (with fixed order for all samples) does not increase the level of challenge as it looks like.

For dataset 3, the difficulty of classification is increased, which can be observed from the degradation of prediction performance (see Table 3). Most models cannot show good prediction performance when the training sample size is small (< 40). Especially for NN and CNN, the degradation of prediction performance is very significant. However, GL still shows good prediction performance even for the small training sample size (< 40). From the histogram of projection of digit matrices (see Fig. 4), it is clear to see the distributions of two classes are overlapped. However, the adaptive threshold (estimated using validation data) can effectively separate the two classes in decision space.

Fig. 5 improves the understanding of the relationship between training sample size and performance indices (SS and SP). The prediction performances of all models are improved by increasing the training sample size. Significant improvements can be found on NN and CNN. Their SS and SP are poor and unstable initially when the training sample size is less than or equal to 40. After increasing the training size to 160, they can achieve performance comparable to SVM and GL (but still inferior to them).

In summary, when the classification problem is simple, SVM shows the best and stable prediction performance. Complex models (e.g., GL and CNN) may overfit the simple problem. On the contrary, when the difficulty of classification increases, GL shows the best prediction performance. Remarkably, when the training sample size is small (< 40), GL still shows excellent prediction performance.

**Table 1.** Prediction performance of four models on dataset 1 (models are trained using five different samples sizes)

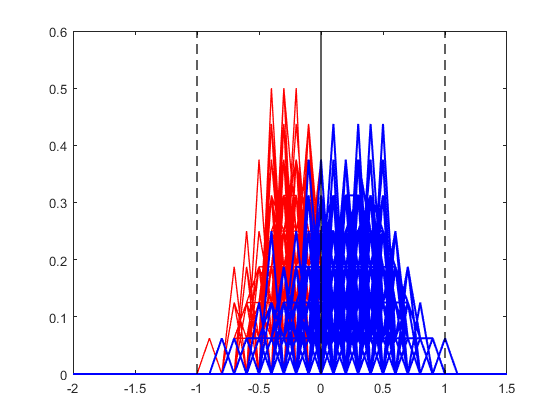
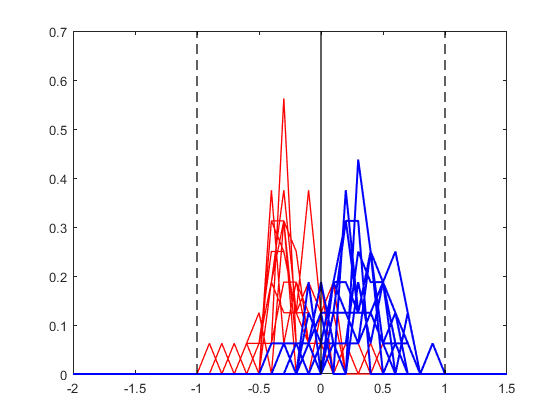
|  |  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- | --- |
| # training samples | SVM | | GL | | NN | | CNN | |
| SS | SP | SS | SP | SS | SP | SS | SP |
| 20 | 1.00±0.00 | 1.00±0.00 | 1.00±0.00 | 0.94±0.04 | 1.00±0.00 | 1.00±0.00 | 0.97±0.06 | 1.00±0.00 |
| 40 | 1.00±0.00 | 1.00±0.00 | 1.00±0.00 | 0.94±0.04 | 1.00±0.00 | 1.00±0.00 | 1.00±0.00 | 0.99±0.01 |
| 80 | 1.00±0.00 | 1.00±0.00 | 1.00±0.00 | 0.98±0.02 | 1.00±0.00 | 1.00±0.00 | 1.00±0.00 | 1.00±0.00 |
| 160 | 1.00±0.00 | 1.00±0.00 | 1.00±0.00 | 0.99±0.01 | 1.00±0.00 | 1.00±0.00 | 1.00±0.00 | 1.00±0.00 |
| 320 | 1.00±0.00 | 1.00±0.00 | 1.00±0.00 | 1.00±0.00 | 1.00±0.00 | 1.00±0.00 | 1.00±0.00 | 1.00±0.00 |

**Table 2.** Prediction performance of four models on dataset 2 (models are trained using five different samples sizes)

|  |  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- | --- |
| # training samples | SVM | | GL | | NN | | CNN | |
| SS | SP | SS | SP | SS | SP | SS | SP |
| 20 | 1.00±0.00 | 1.00±0.00 | 1.00±0.00 | 0.93±0.03 | 0.98±0.04 | 0.99±0.02 | 0.99±0.01 | 0.98±0.03 |
| 40 | 1.00±0.00 | 1.00±0.00 | 1.00±0.00 | 0.95±0.02 | 1.00±0.00 | 0.99±0.01 | 1.00±0.00 | 0.99±0.01 |
| 80 | 1.00±0.00 | 1.00±0.00 | 1.00±0.00 | 0.99±0.01 | 1.00±0.00 | 1.00±0.00 | 1.00±0.00 | 1.00±0.00 |
| 160 | 1.00±0.00 | 1.00±0.00 | 1.00±0.00 | 0.99±0.01 | 1.00±0.00 | 1.00±0.00 | 1.00±0.00 | 1.00±0.00 |
| 320 | 1.00±0.00 | 1.00±0.00 | 1.00±0.00 | 1.00±0.01 | 1.00±0.00 | 1.00±0.00 | 1.00±0.00 | 1.00±0.00 |

**Table 3.** Prediction performance of four models on dataset 3 (models are trained using five different samples sizes)

|  |  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- | --- |
| # training samples | SVM | | GL | | NN | | CNN | |
| SS | SP | SS | SP | SS | SP | SS | SP |
| 20 | 0.91±0.02 | 0.82±0.05 | 1.00±0.00 | 0.96±0.03 | 0.87±0.14 | 0.62±0.25 | 0.72±0.29 | 0.61±0.37 |
| 40 | 0.96±0.02 | 0.89±0.04 | 1.00±0.00 | 0.96±0.03 | 0.77±0.25 | 0.80±0.18 | 0.99±0.01 | 0.55±0.18 |
| 80 | 0.97±0.01 | 0.97±0.01 | 1.00±0.00 | 0.98±0.03 | 0.96±0.02 | 0.94±0.02 | 0.97±0.03 | 0.95±0.02 |
| 160 | 0.99±0.01 | 0.99±0.00 | 1.00±0.00 | 0.98±0.01 | 0.97±0.02 | 0.98±0.02 | 0.98±0.01 | 0.97±0.01 |
| 320 | 1.00±0.00 | 0.99±0.01 | 1.00±0.00 | 1.00±0.00 | 1.00±0.00 | 0.97±0.02 | 0.99±0.00 | 0.99±0.00 |



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**Fig. 4.** Histograms for digit matrices in dataset 3 and the corresponding decision space for discriminating between positive and negative. Adaptive thresholds are indicated as dashed lines. Histograms for 20 training samples (upper left); Histograms for 1000 test samples (upper right); Decision space for training samples (bottom left); Decision space for test samples (bottom right).

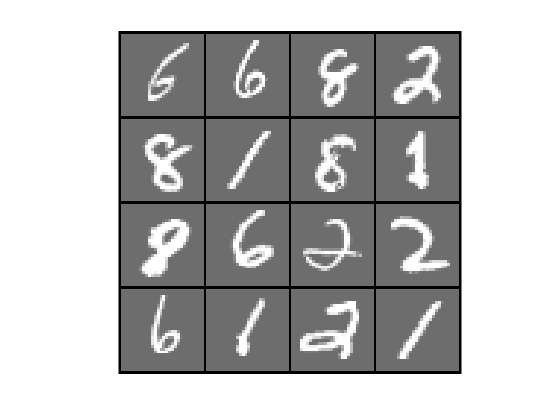
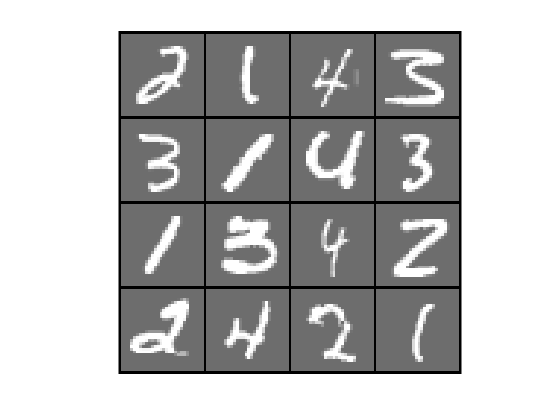
**Fig. 5.** The test SS(left) and SP(right) as a function of training sample size of dataset 3 for four models (SVM, GL, NN, and CNN).

**Result 2: Prediction performance of four models (SVM, GL, NN, CNN) on high overlapped dataset (50% overlap)**

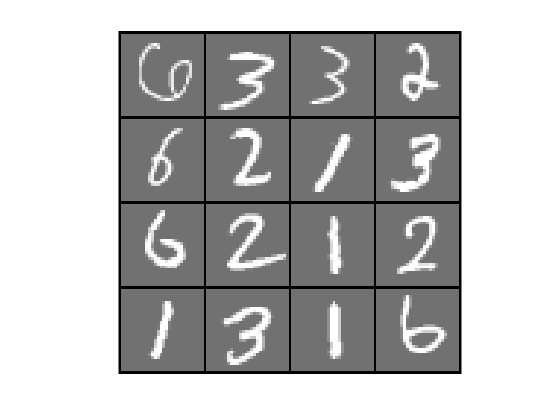
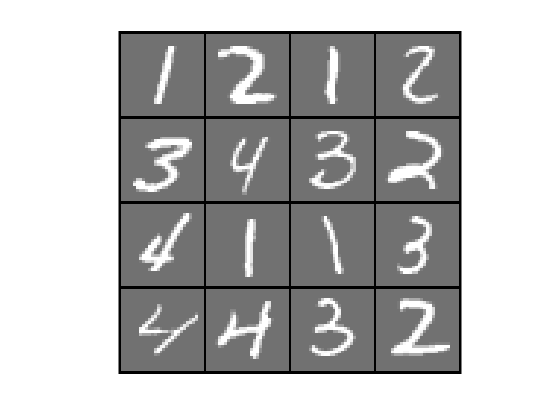
In the previous section, we have investigated the prediction performance on the low overlapped dataset (i.e., dataset 3 with 25% overlap). In this section, we further investigate the prediction performance of four models on digit matrices with high overlap. The dataset with 50% overlap is generated by changing the digits composing Dataset 3 (i.e., positive class: digits ‘1, 2, 6, 8’, negative class: digits ‘1, 2, 3, 4’ – see Fig. 6).

The prediction performance of four models on the high overlapped dataset is shown in Table 4. Note that the training error is close to zero; hence, only the test result is presented. Clearly, the prediction performance is decreased by increasing the overlap for most models.

Figs. 8 shows the relationship between training sample size and performance indices in Tables 4, which helps to observe the prediction performance under different training sample sizes for four models. Overall, GL shows the best prediction performance, especially when the training sample size is small (< 40). The high overlap seems not to affect the prediction performance of GL. The histograms of the two classes are shown in Fig. 9. The overlap of the two classes is even severe compared to dataset 3 with 25% overlap (see Fig. 4). However, the adaptive threshold can still correctly classify the two classes in the decision space. On the contrary, the high overlap affects the prediction performance of other models greatly, especially when the training sample size is small—their SPs decay significantly to 0.60 and under.

**Fig. 6.** Dataset 3 (with 50% overlap), examples in positive (left) and negative (right) classes

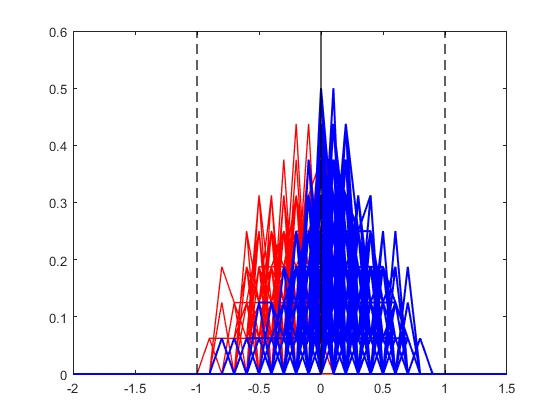
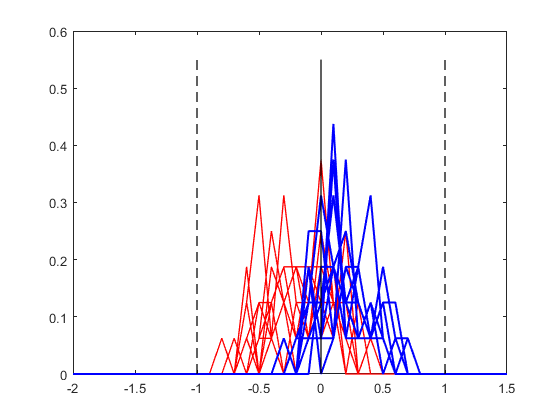
 

**Fig. 7.** Dataset 3 (with 75% overlap), examples in positive (left) and negative (right) classes

**Table 4.** Prediction performance of four models on dataset 3 with 50% overlap (models are trained using five different samples sizes)

|  |  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- | --- |
| # training samples | SVM | | GL | | NN | | CNN | |
| SS | SP | SS | SP | SS | SP | SS | SP |
| 20 | 0.89±0.04 | 0.59±0.06 | 1.00±0.00 | 0.90±0.07 | 0.91±0.16 | 0.26±0.33 | 0.80±0.31 | 0.44±0.37 |
| 40 | 0.89±0.04 | 0.81±0.05 | 1.00±0.00 | 0.97±0.04 | 0.83±0.21 | 0.62±0.25 | 0.90±0.07 | 0.70±0.12 |
| 80 | 0.93±0.04 | 0.89±0.04 | 1.00±0.00 | 0.97±0.01 | 0.93±0.09 | 0.66±0.32 | 0.93±0.04 | 0.90±0.04 |
| 160 | 0.96±0.04 | 0.97±0.00 | 1.00±0.00 | 0.98±0.02 | 0.89±0.13 | 0.86±0.15 | 0.96±0.03 | 0.94±0.04 |
| 320 | 0.97±0.03 | 0.99±0.00 | 1.00±0.00 | 0.99±0.01 | 0.99±0.00 | 0.93±0.05 | 0.99±0.00 | 0.99±0.01 |

**Fig. 8.** The test SS(left) and SP(right) as a function of training sample size of dataset 3 (50% overlap) for four models (SVM, GL, NN, and CNN).



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**Fig. 9.** Histograms for digit matrices in dataset 3 (50% overlap) and the corresponding decision space for discriminating between positive and negative. Adaptive thresholds are indicated as dashed lines. Histograms for 20 training samples (upper left); Histograms for 1000 test samples (upper right); Decision space for training samples (bottom left); Decision space for test samples (bottom right)

**Result 3: Group Learning using different window sizes**

In this section, we apply Group Learning on dataset 3 (see Fig. 3) using different window sizes. The hand-written digit image is of size 28\*28 pixels. This prior knowledge of digit data is applied to Group Learning for choosing window size as 28\*28 pixels in the previous experiments. That is, the training of model is based on 28\*28 windows. Here, we apply different window sizes to Group Learning to assess prediction performance's effect on varied window sizes. The experimental settings are the same as those used in the previous sections. The numbers of training data and validation data are 20 (10 for each class), the number of test data is 1000 (500 for each class), and each experiment is repeated five times.

Two types of window are applied to the 16-digit images (112\*112 pixels):

1. Divisor window (which can divide the 16-digit images, see examples in Fig. 10): 7\*7, 14\*14, 28\*28, 56\*56.
2. Non-divisor window (which cannot divide the 16-digit images, and the remainder would be removed, see examples in Fig. 11): 10\*10, 20\*20, 30\*30, 40\*40, 50\*50.

The prediction results (average SS, SP) of GL applying divisor windows are shown in Fig. 12. The SS and SP for training data are generally high for all divisor windows (> 0.97). Only the SP for the 7\*7 window is slightly lower (0.92). The SS and SP are also high for all divisor windows (> 0.93), only for the small window size 7\*7, the SP is 0.79. Especially for the large window size 56\*56, the SP is even better than the 28\*28 widow (the size of single digits). The results suggest that the size of divisor windows should be large enough to contain enough information for prediction. Using small window size (such as 7\*7) may hurt the prediction performance of GL.

The prediction results (average SS, SP) of GL using non-divisor windows are shown in Fig. 13. The SS and SP for training data are also high (> 0.94), except for the small 10\*10 windows. However, the SS, SP for test data are generally low. Even for the large window (50\*50), the SP is still low (~0.39). The poor prediction performance may result in the corrupted information of the non-divisor windows, shown in Fig 11. These non-divisor windows contain mixed/shifted digit parts. Additionally, the great amount of reminders (of the 16-digit images) is removed.

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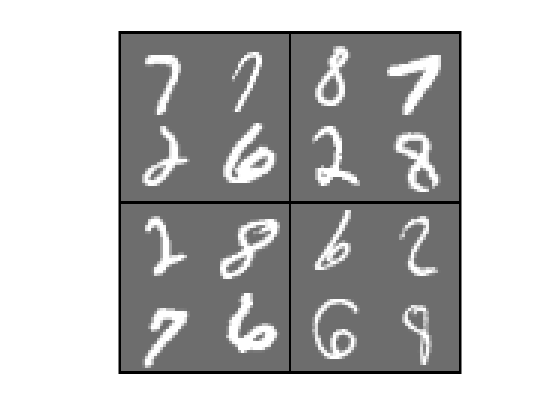
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Fig. 10. 16-digit image with divisor window, 14\*14 window (left), and 56\*56 window (right)

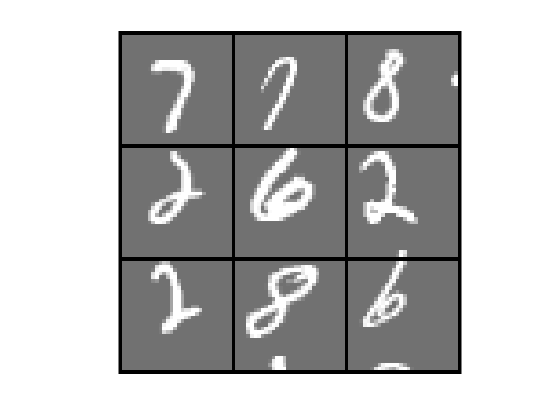
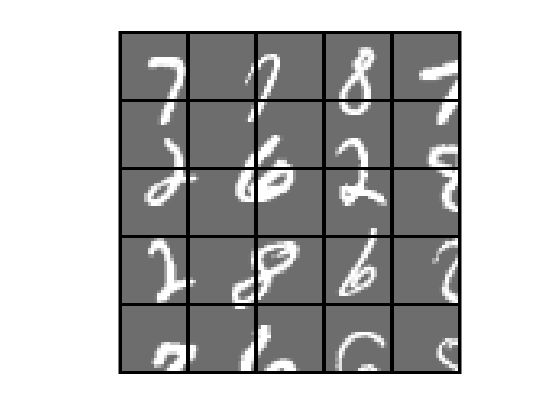


Fig. 11. 16-digit image with non-divisor window, 20\*20 window (left), and 30\*30 window (right). The reminders are removed.

Fig. 12. Prediction performance (average SS, SP of five repeats) of GL using different divisor windows (of sizes 7\*7, 14\*14, 28\*28, 56\*56) on dataset 3. (a) Training data, (b) Test data.

(a)

(b)

Fig. 13. Prediction performance (average SS, SP of five repeats) of GL using different non-divisor windows (of sizes 10\*10, 20\*20, 30\*30, 40\*40, 50\*50) on dataset 3. (a) Training data, (b) Test data.

**Results 4: Group Learning for unbalanced datasets (reported in Cherkassky et al., 2019)**

**Result 5: Application of Group learning in real datasets**

Group Learning is applied to two real datasets. Both two datasets have high dimensional features and imbalanced classes. The information of the two datasets are as follows:

**iEEG data: (detailed information in Cherkassky et al., 2019)**

*Positive class:* 4-hr preictal iEEG segments

*Negative class:* 4-hr interictal iEEG segments

Ratio between positive and negative samples: 1:8

**Gene expression data: (detailed information in Ramaswamy et al., 2003, Díaz-Uriarte et al., 2006)**

*Positive class:* metastatic adenocarcinoma

*Negative class:* primary adenocarcinomas

Ratio between positive and negative samples: 12:64

Table 1. Prediction performance of Group Learning applied in real data sets

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| Data set | Prior knowledge | SVM | | Group Learning | |
| SS | SP | SS | SP |
| iEEG | Median | Nan\* | Nan\* | 0.89 | 0.87 |
| Gene expression | Weak | 0.25 | 1.00 | 0.44 | 0.95 |

\*The feature dimension of iEEG samples (i.e., 4hr segment) is too high for SVM

Reference:

1. Cherkassky, Vladimir, Hsiang-Han Chen, and Han-Tai Shiao. "Group Learning for High-Dimensional Sparse Data." *2019 International Joint Conference on Neural Networks (IJCNN)*. IEEE, 2019.
2. Ramaswamy, Sridhar, et al. "A molecular signature of metastasis in primary solid tumors." *Nature genetics* 33.1 (2003): 49-54.
3. Díaz-Uriarte, Ramón, and Sara Alvarez De Andres. "Gene selection and classification of microarray data using random forest." *BMC bioinformatics* 7.1 (2006): 3.